

ECONOMIC JUSTIFICATION

OF

INDUSTRIAL ROBOTS

MANAGEMENT OVERVIEW

- I. INTRODUCTION
- II. DISCUSSION OF KEY ISSUES IN
ROBOT APPLICATIONS
- III. ANALYSIS TOOLS
- IV. SUMMARY

MAJOR DETERENTS TO
ROBOT APPLICATION INVESTIGATIONS

- WHERE TO BEGIN
- IDENTIFYING GOOD APPLICATIONS
- ESTABLISHING RESPONSIBILITIES
- SECONDARY TO MEETING PRODUCTION
- MANPOWER

PURPOSE OF THE PRESENTATION

- ATTEMPT TO CLARIFY THE JUSTIFICATION PROCESS
- PROVIDE ANALYTICAL TOOLS TO ASSIST ENGINEERS
- MAKE THE INITIAL INVESTIGATION FASTER
- DEVELOP A METHODOLOGY FOR THE INVESTIGATION

GOALS

- MORE EFFICIENT USE OF ENGINEERS
- CONSTRUCT THE APPLICATION TO ACHIEVE THE LOWEST MANUFACTURING COST
- PROVIDE INITIAL DIRECTION (GO/NO-GO)
- IDENTIFY THE BEST APPLICATIONS

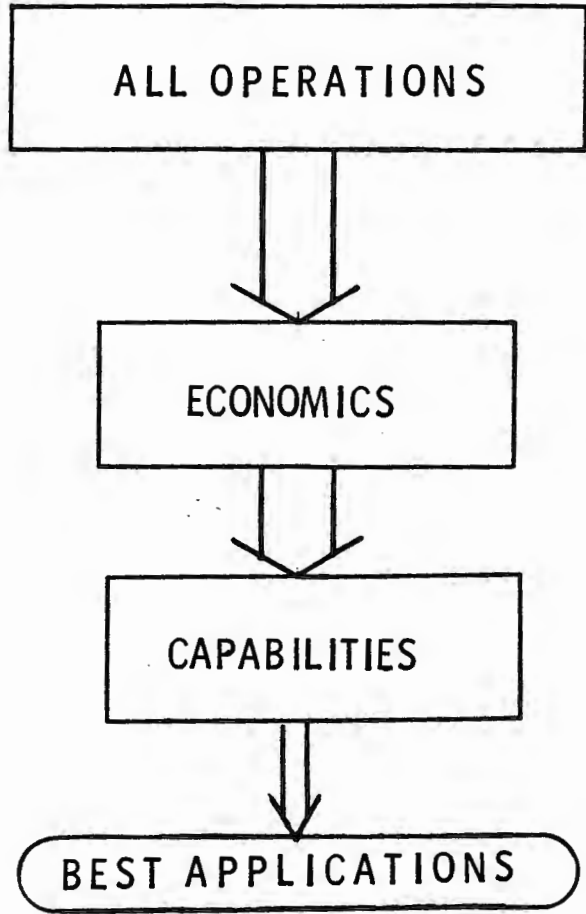
ROBOT APPLICATION?

EQUIPMENT
CAPABILITIES

ECONOMICS

ROBOT CAPABILITIES
MACHINE TOOLS OR PROCESS
PART ORIENTATION DEVICES
SENSORS
MAINTENANCE
SPACE REQUIREMENTS

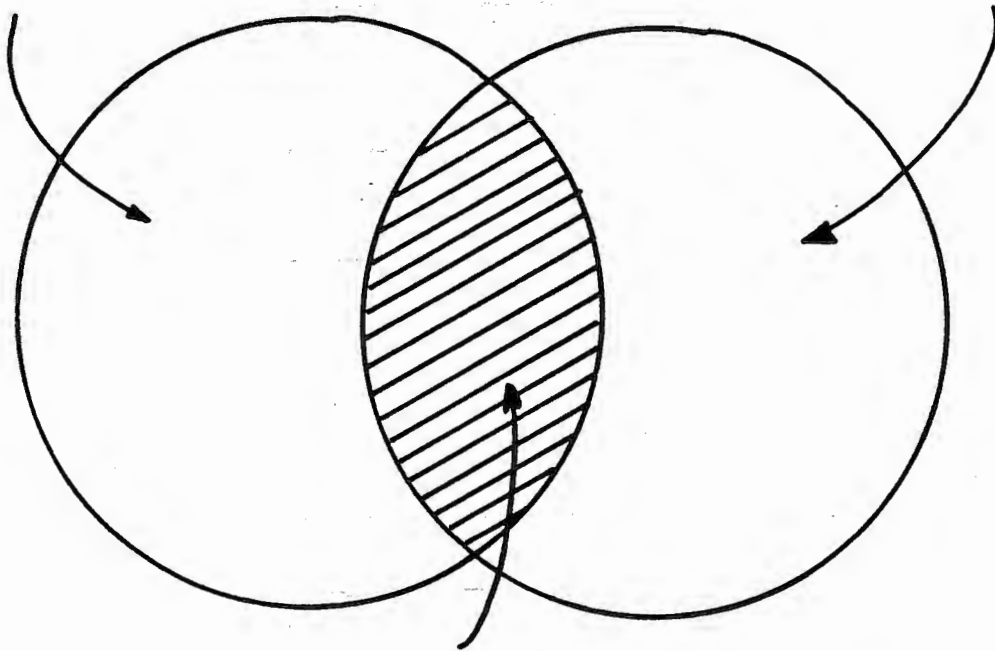
CAPITAL EXPENDITURES
SAVINGS
R. O. I.
RISK
PRODUCTIVITY



TECHNICAL FEASIBILITY/ECONOMIC FEASIBILITY RELATIONSHIP

Operations that are technically
feasible

Operations that are economically
feasible



Operations that are both technically and economically feasible

ROBOT CAPABILITIES

ROBOTS CAN DO PRACTICALLY ANYTHING YOU WANT
THEM TO DO

ROBOTS CAN DO PRACTICALLY ANYTHING YOU WANT THEM
TO DO AND ARE WILLING TO PAY FOR

WHAT IS ECONOMIC JUSTIFICATION?

- CRITERIA FOR DECISIONS

- RELATIVE MEASURE
 - INDUSTRY TO INDUSTRY
 - COMPANY TO COMPANY
 - FACTORY TO FACTORY

- COMPARATIVE MEASURE

COSTS OF ROBOT SYSTEMS — Included Items

- ROBOT
- FIXTURING AND ORIENTING DEVICES
- INTERFACING SUPPLIES
- TRAINING
- SPARE PARTS
- TOOLING
- CONVEYORS AND RACKS
- MACHINE TOOL REVISIONS
- SAFETY EQUIPMENT
- INSTALLATION
- TAXES
- FREIGHT
- DESIGN
- LESS TAX CREDIT

SAVINGS AND EXPENSES IN NORMAL
ROBOT APPLICATIONS

SAVINGS

EXPENSES

EITHER WAY

Direct Labor

Maintenance Labor

* Indirect Labor

Farmout Reduction

* Part Redesigns

Energy

Direct Material

Training

Floor Space

* Indirect Material

* M. E. Support

* Downtime

* Quality

* WIP

OSHA Compliance

Scrap Reduction

Resale of Old Equip.

Depreciation Costs

INTANGIBLES

* Safety

* Better Management Control

* Inflation

* Less Human Problems

* Step In The Right Direction For Future

* Capacity

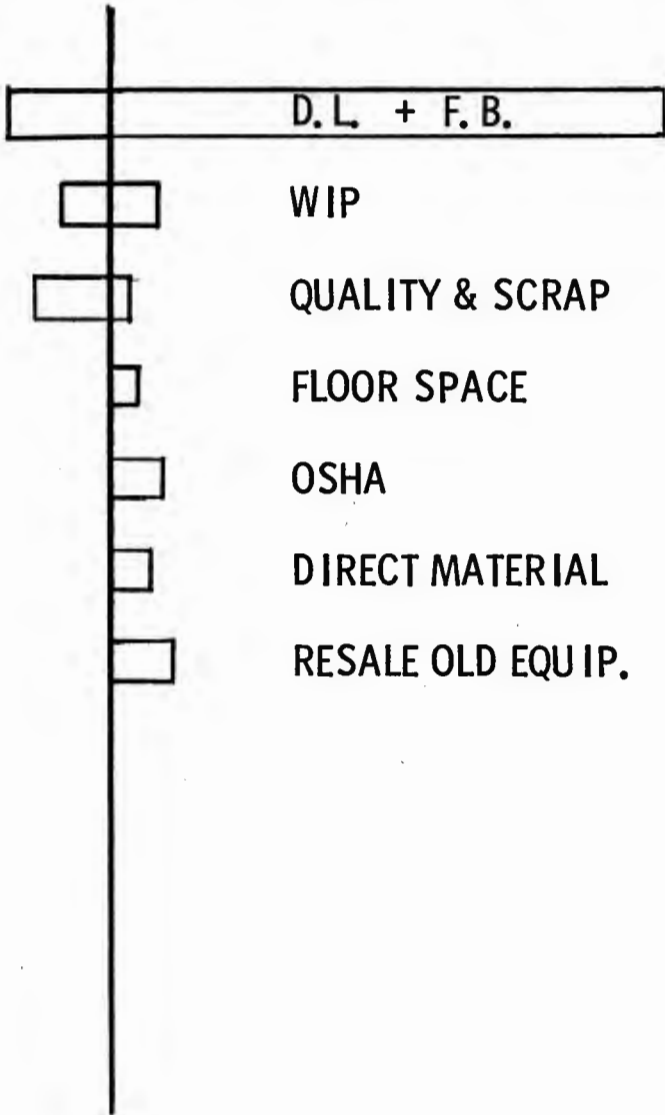
* Maintaining State of the Art

* Meeting Product Demand

* ITEMS THAT ARE NOT NORMALLY INCLUDED ON AFE/DCF
UNLESS SPECIFICALLY IDENTIFIABLE

SAVINGS VS. EXPENSES

SAVINGS



EXPENSES

MAINTENANCE

TRAINING

DOWNTIME

D.L. + F.B.

WIP

QUALITY & SCRAP

FLOOR SPACE

OSHA

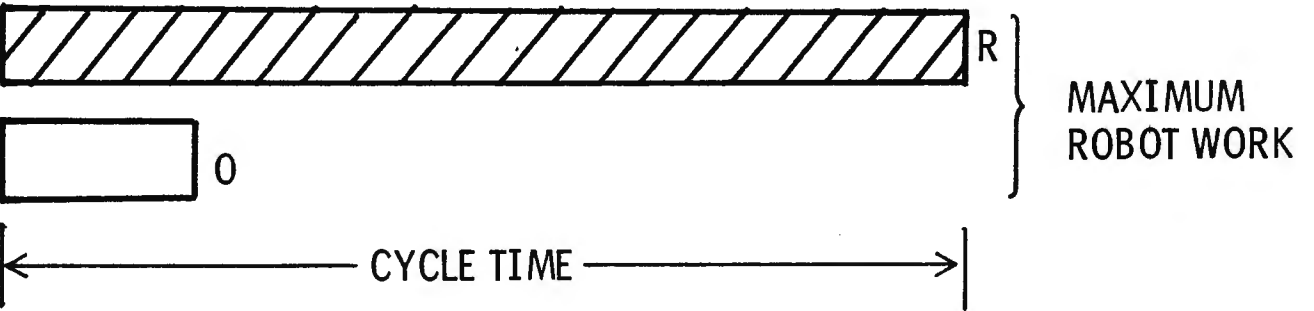
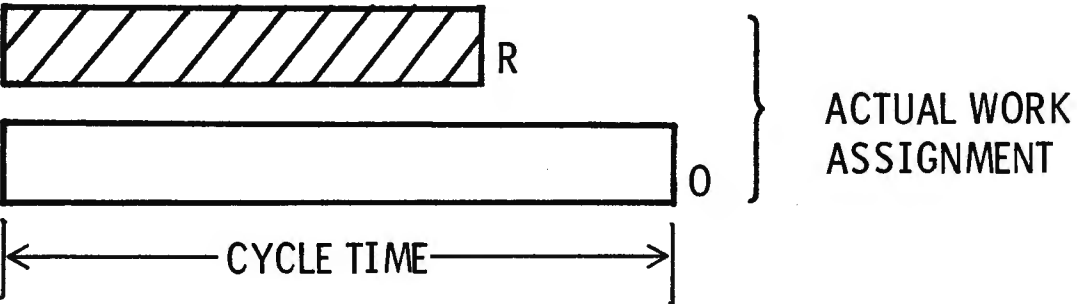
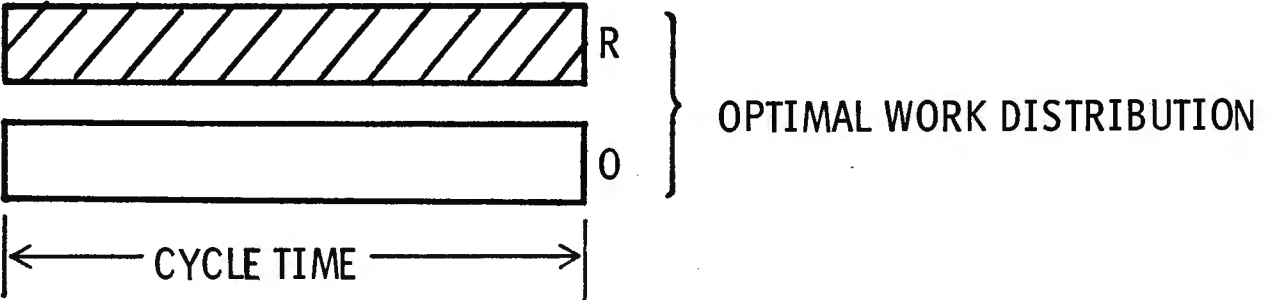
DIRECT MATERIAL

RESALE OLD EQUIP.

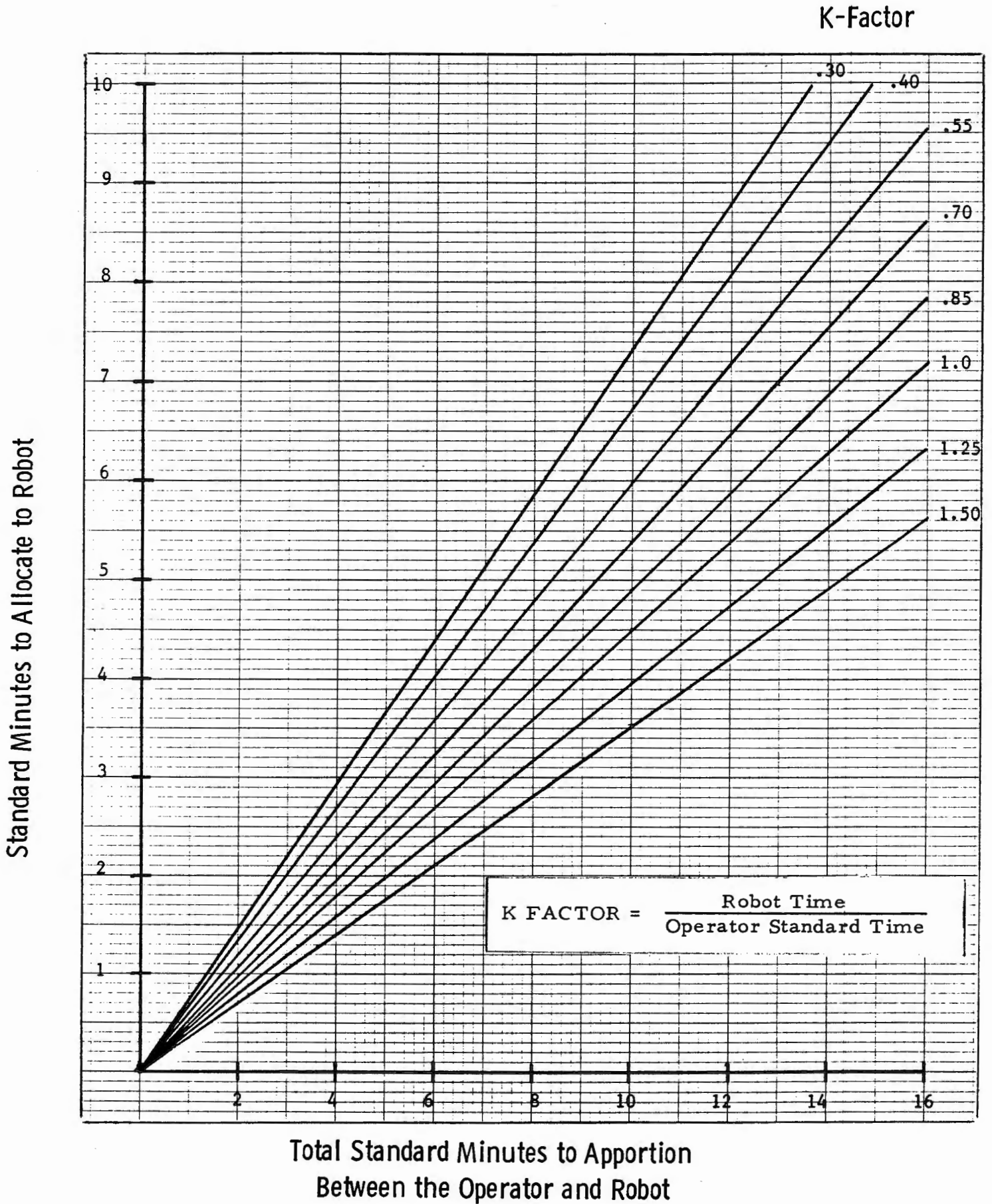
ASSUMPTIONS IN ROBOT ANALYSIS

- AN OPERATOR WILL BE ASSIGNED TO THE OPERATION
- IT IS PREFERABLE THAT THE OPERATION REMAIN ON INCENTIVE
- THE OPERATOR SHOULD BE GIVEN 130% INCENTIVE OPPORTUNITY
- SAFETY DEVICES WILL BE SUFFICIENT TO ALLOW THE OPERATOR AND ROBOT TO WORK IN THE SAME CELL

ROBOT WORK ELEMENT DISTRIBUTION
GRAPHIC DISPLAY
(SINGLE ROBOT SYSTEM)

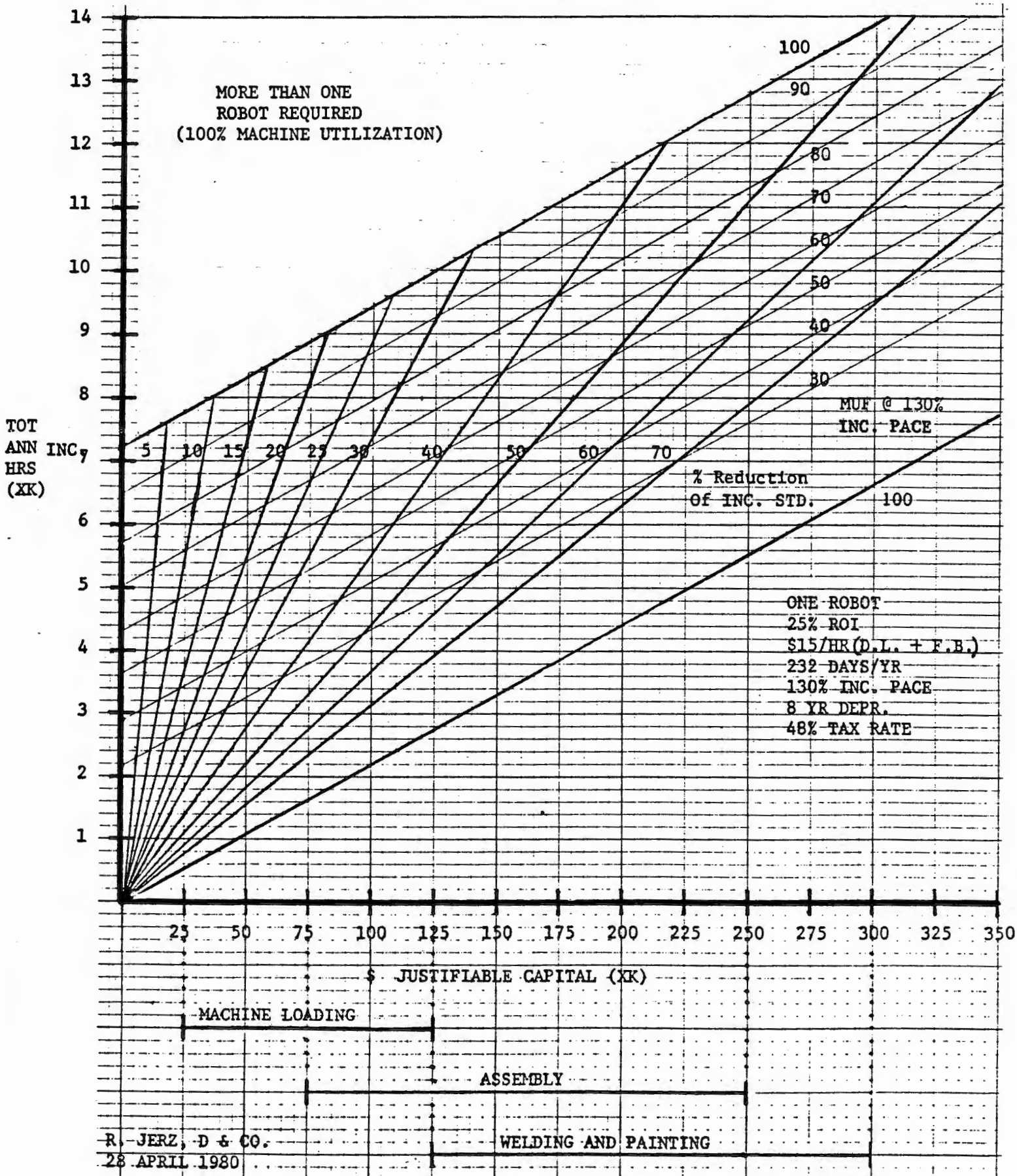


Optimal Division of Total Standard Minutes (at 1, 15 Avg. P&F Factor)



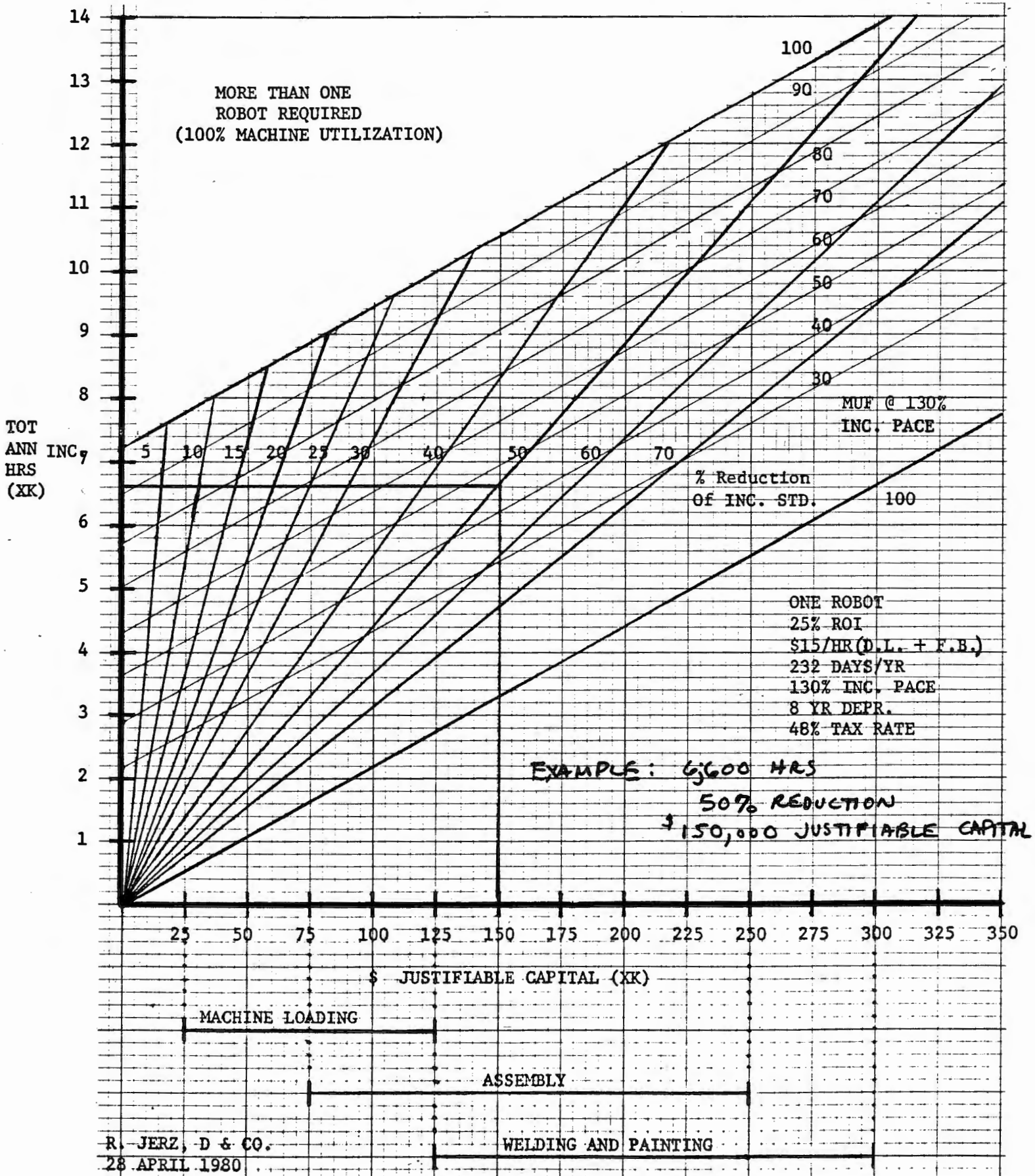
ROBOT ANALYSIS -- U.S. FACTORIES

TOTAL ANNUAL HOURS VS. JUSTIFIABLE CAPITAL EXPENDITURE
 (@ % DIRECT LABOR REDUCTION AND % MACHINE UTILIZATION)



ROBOT ANALYSIS -- U.S. FACTORIES

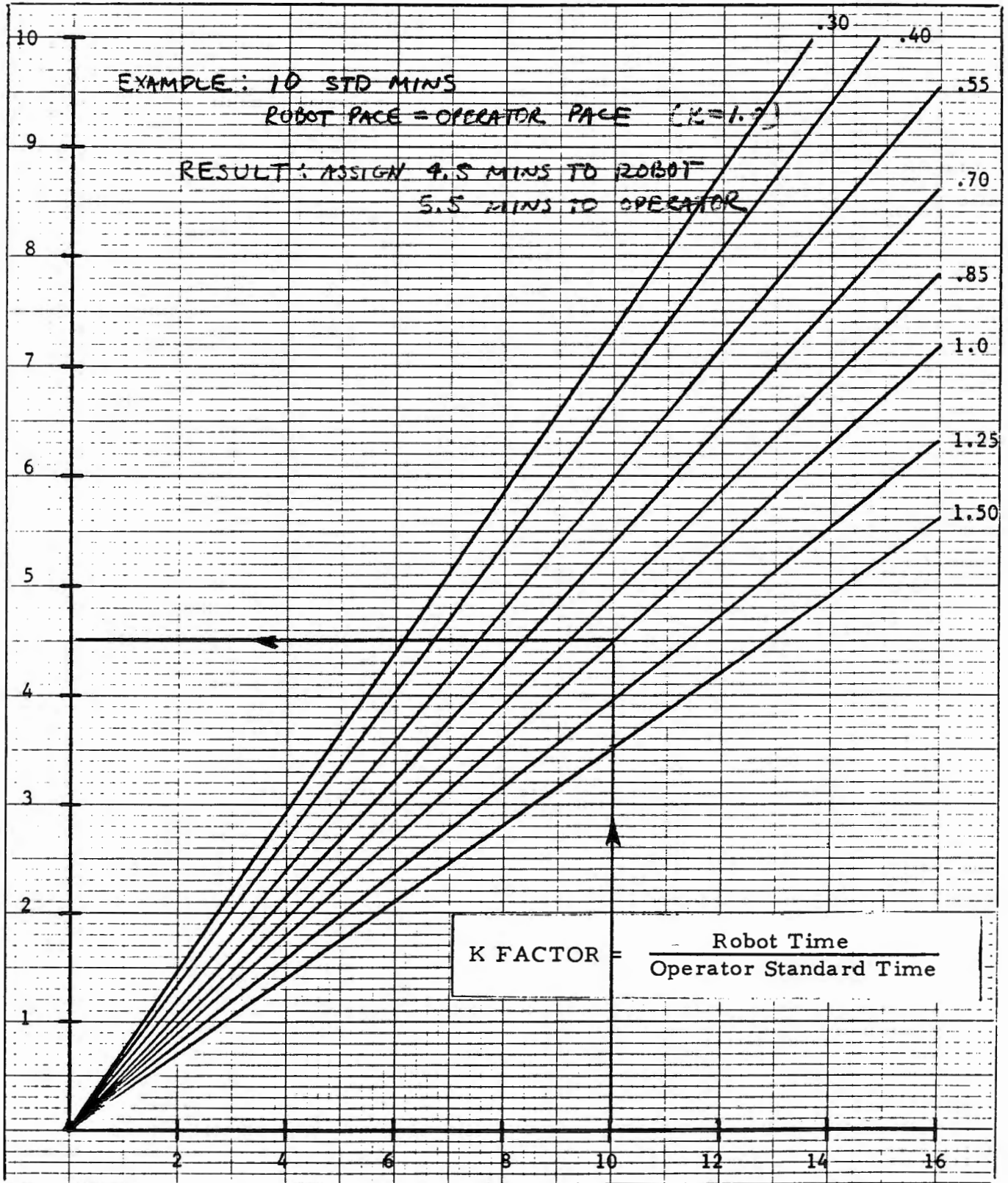
TOTAL ANNUAL HOURS VS. JUSTIFIABLE CAPITAL EXPENDITURE
 (@ % DIRECT LABOR REDUCTION AND % MACHINE UTILIZATION)



Optimal Division of Total Standard Minutes (at 1, 15 Avg. P&F Factor)

K-Factor

Standard Minutes to Allocate to Robot

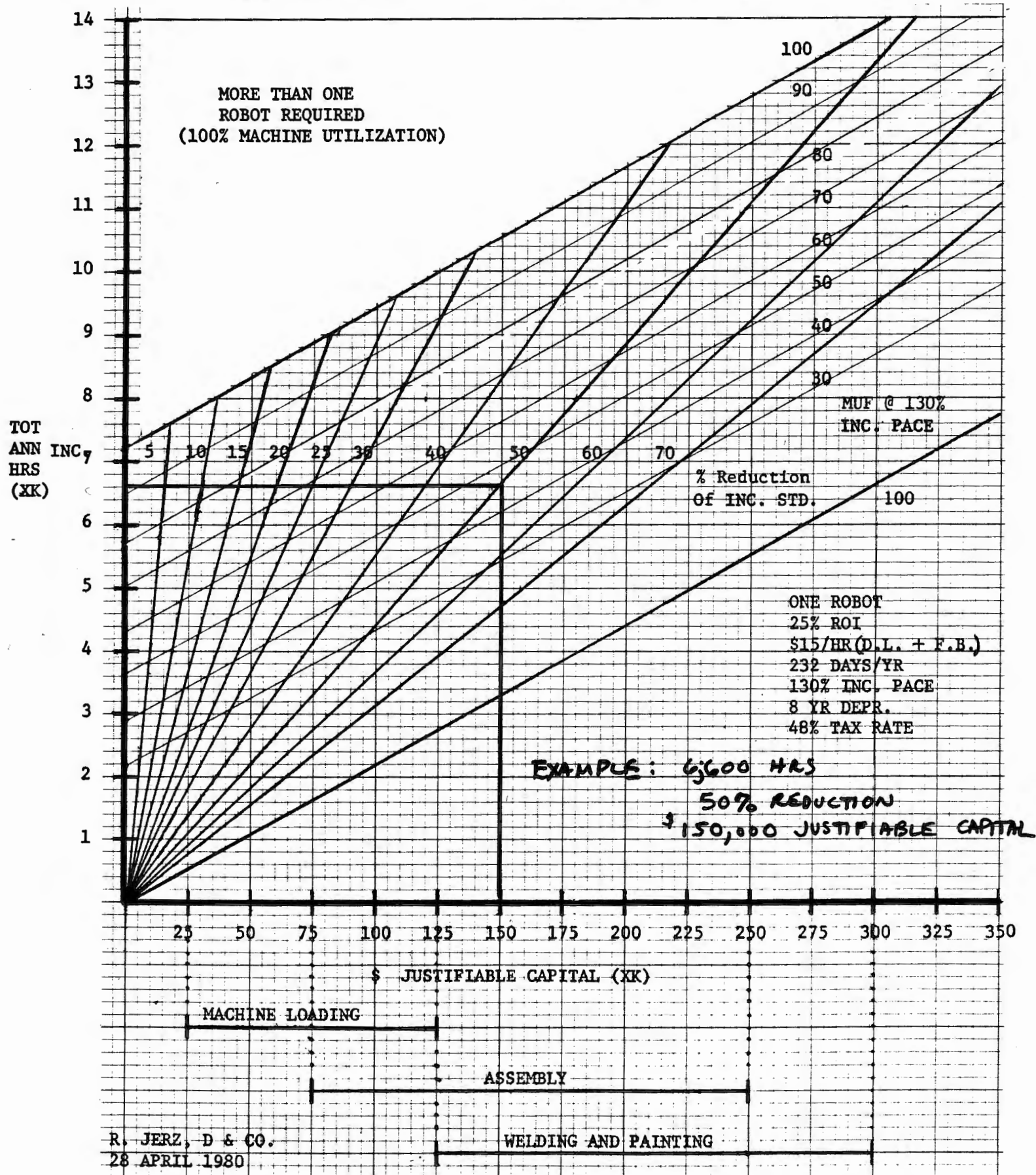


$$K \text{ FACTOR} = \frac{\text{Robot Time}}{\text{Operator Standard Time}}$$

Total Standard Minutes to Apportion Between the Operator and Robot

ROBOT ANALYSIS -- U.S. FACTORIES

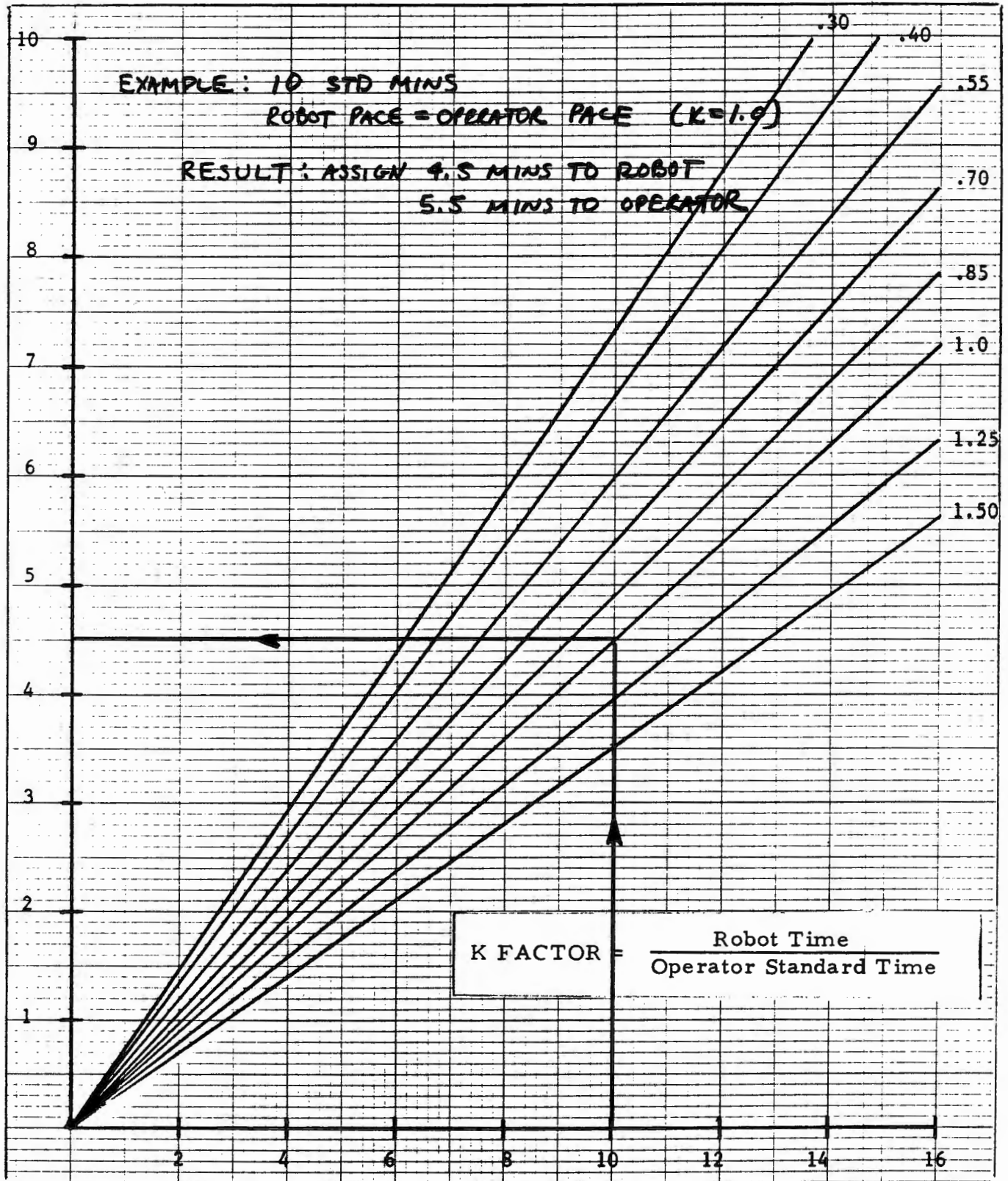
TOTAL ANNUAL HOURS VS. JUSTIFIABLE CAPITAL EXPENDITURE
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Optimal Division of Total Standard Minutes (at 1, 15 Avg. P&F Factor)

K-Factor

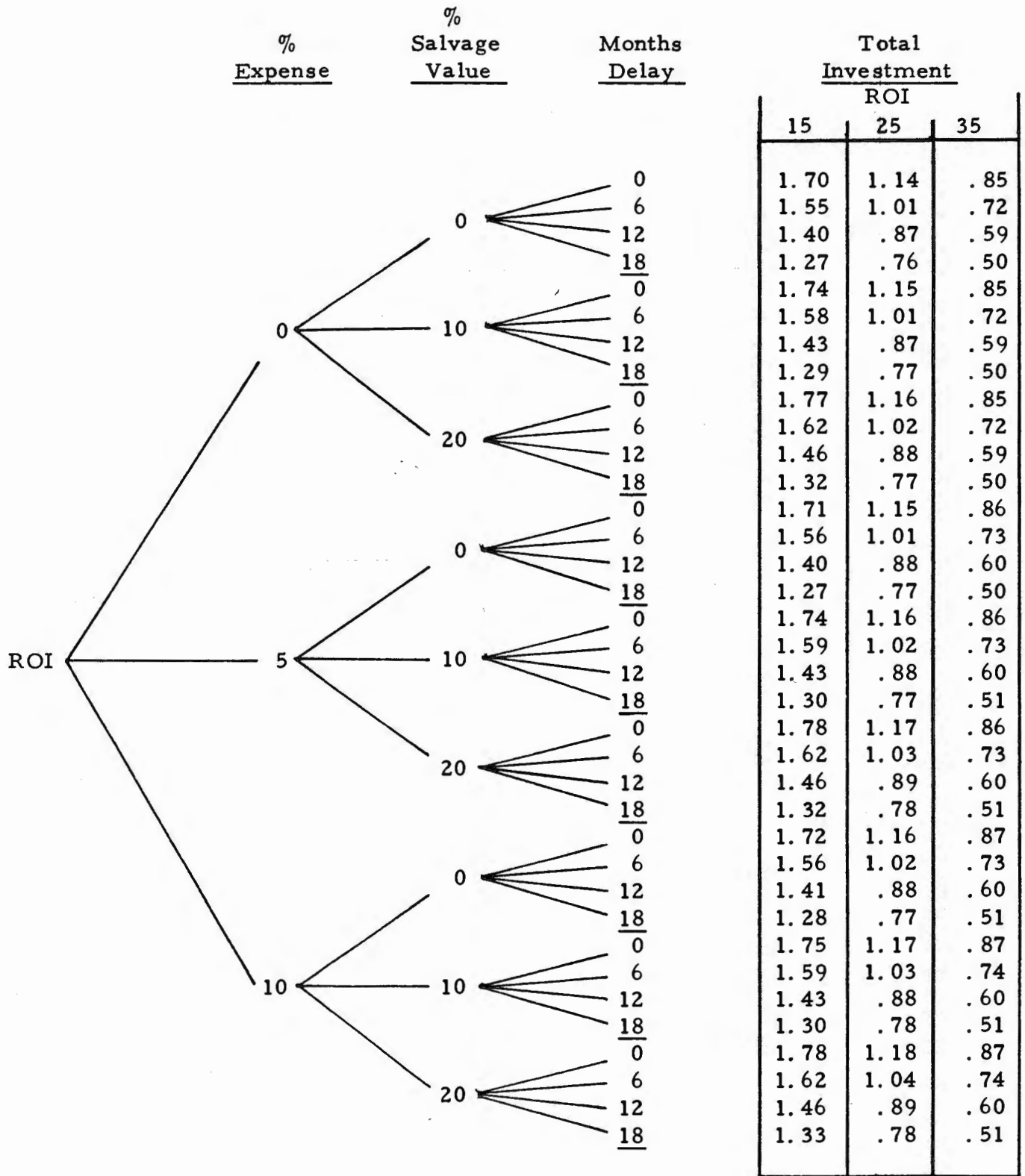
Standard Minutes to Allocate to Robot



$$K \text{ FACTOR} = \frac{\text{Robot Time}}{\text{Operator Standard Time}}$$

Total Standard Minutes to Apportion Between the Operator and Robot

Total Investment Conversion Chart



EXAMPLE

HOT FORMING SCRAPER BLADES

CURRENT OPERATION

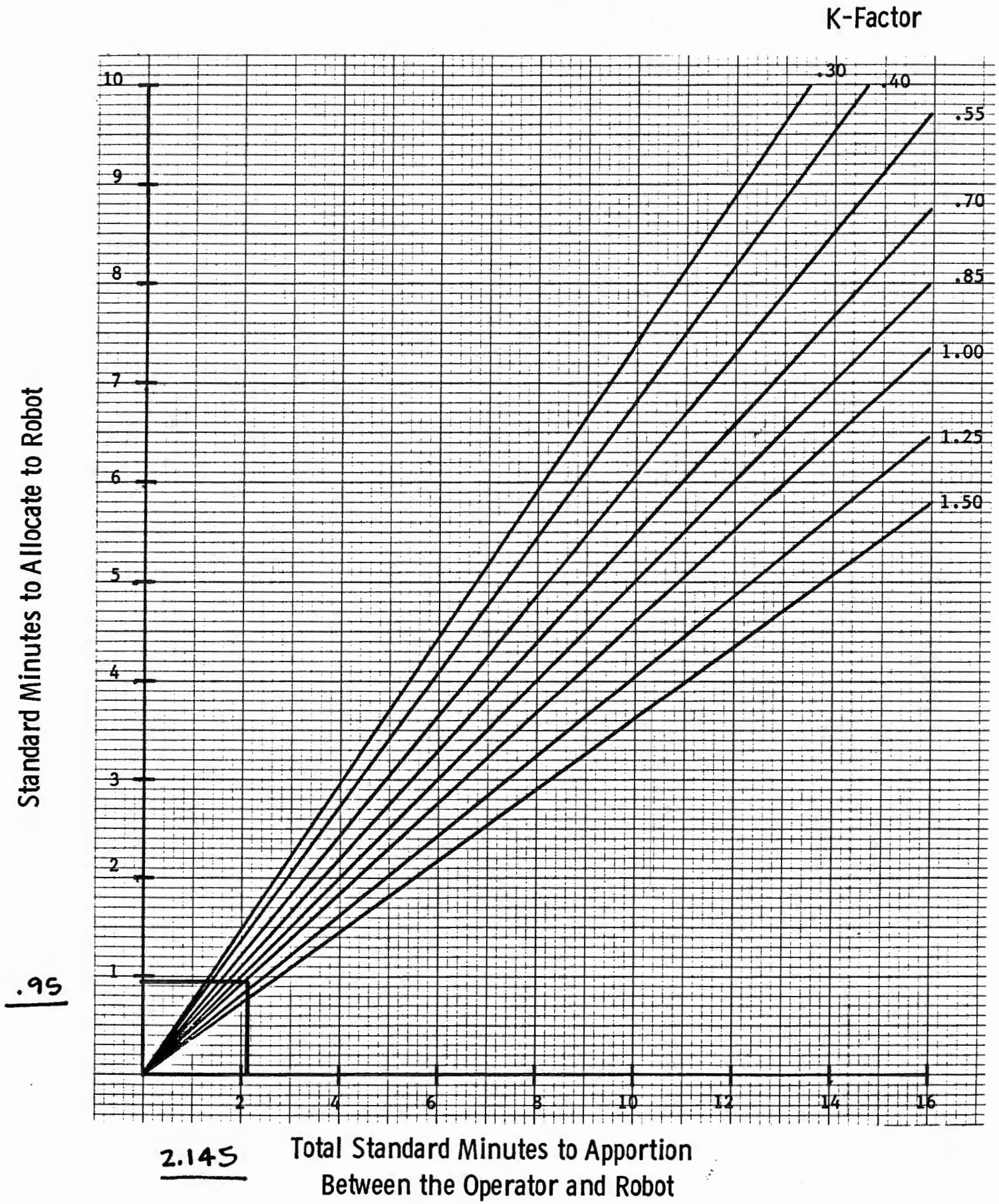
1 OPERATOR

4 PART NUMBERS

8104 YEARLY INCENTIVE HOURS

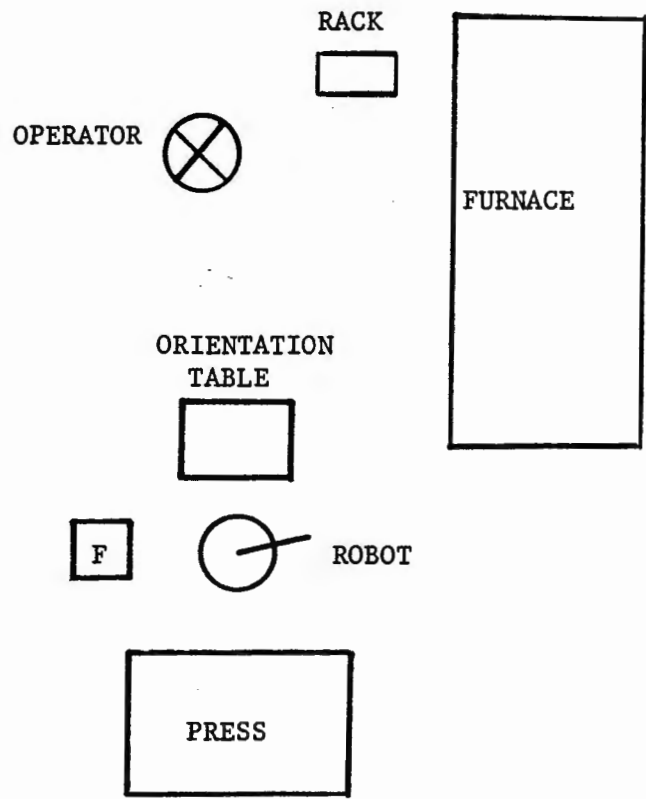
2.145 STANDARD MINUTES PER PART

Optimal Division of Total Standard Minutes (at 1.20 Avg. P&F Factor)



HOT FORMING OF SCRAPER BLADES

ROBOT APPLICATION



OPTIMAL WORK DISTRIBUTION

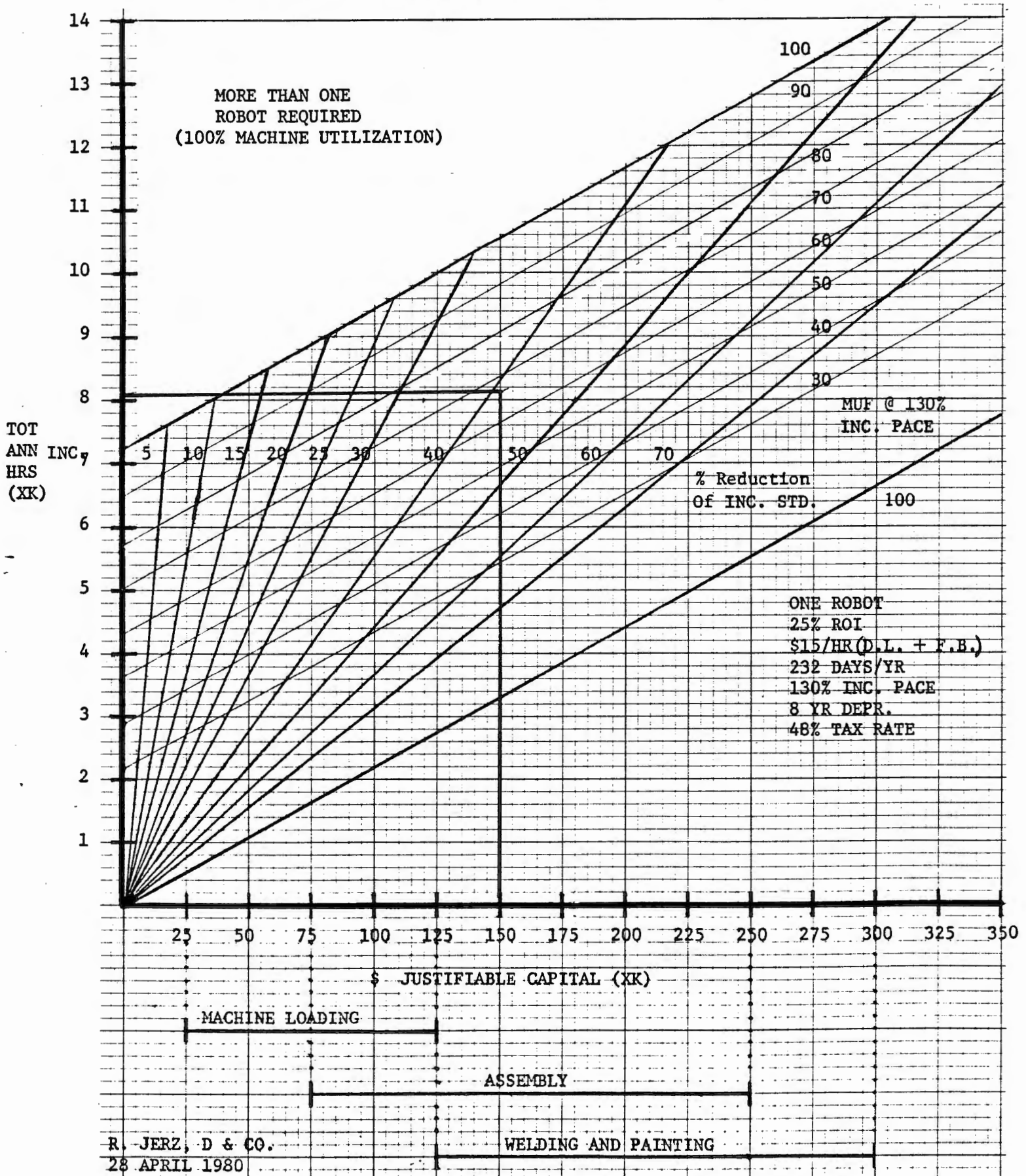
.95 MINS. TO ROBOT
1.20 MINS. TO OPERATOR

ACTUAL WORK DISTRIBUTION

1.27 MINS TO OPERATOR
40.8 % LABOR REDUCTION

ROBOT ANALYSIS -- U.S. FACTORIES

TOTAL ANNUAL HOURS VS. JUSTIFIABLE CAPITAL EXPENDITURE
 (@ % DIRECT LABOR REDUCTION AND % MACHINE UTILIZATION)



RESULTS:

\$150,000 JUSTIFIABLE CAPITAL

@ 25% ROI

67% MUF

LOW HOUR ANALYSIS OVERVIEW

OBJECTIVE: TO ANALYTICALLY DETERMINE THE YEARLY HOURS THAT AN OPERATION MUST RUN BEFORE IT BECOMES ECONOMICALLY FEASIBLE TO AUTOMATE IT.

LOW HOUR ANALYSIS

EXAMPLE - WELDING

NUMBER OF SET UPS PER YEAR	-	6
SET UP TIME FOR OPERATION	-	$3/4$ HR
SET UP TIME FOR ROBOT	-	$1/2$ HR
INCREMENTAL TOOLING COST	-	\$15 K
ROBOT COST	-	\$100 K
DIRECT LABOR COST PLUS F.B.	-	\$15 /HR
PAYBACK FACTOR	-	3.0
PERCENT LABOR REDUCTION	-	45
PERCENT DELAYS	-	20

$$\underline{\text{YEARLY HOURS}} = 1223$$

$$\underline{\# \text{ OF PARTS}} = 10.5$$

LOW HOUR ANALYSIS

EXAMPLE - MACHINE LOADING

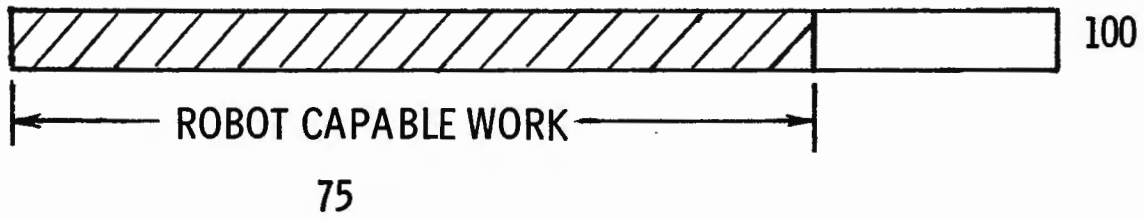
NUMBER OF SET UPS PER YEAR	-	12
SET UP TIME FOR OPERATION	-	1/2 HR
SET UP TIME FOR ROBOT	-	1/2 HR
INCREMENTAL TOOLING COST	-	\$4 K
ROBOT COST	-	\$75 K
DIRECT LABOR COST PLUS F.B.	-	\$15/HI
PAYBACK FACTOR	-	3.0
PERCENT LABOR REDUCTION	-	45
PERCENT DELAYS	-	25

$$\underline{\text{YEARLY HOURS}} = 309.6$$

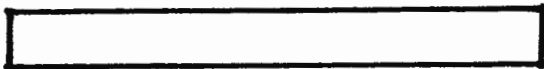
$$\underline{\text{\# OF PARTS}} = 37.51$$

ONE ROBOT/ONE OPERATOR

ALL WORK CURRENTLY BEING PERFORMED



OPTIMAL DISTRIBUTION 50/50



← CYCLE TIME = 50 →

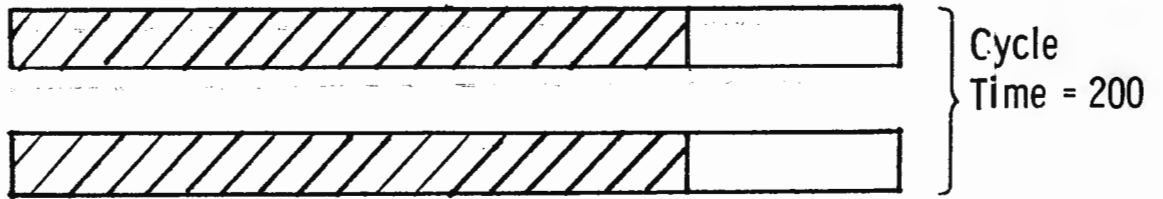
SAVINGS = 50

DUPLICATE SYSTEM (SUB-OPTIMIZATION)

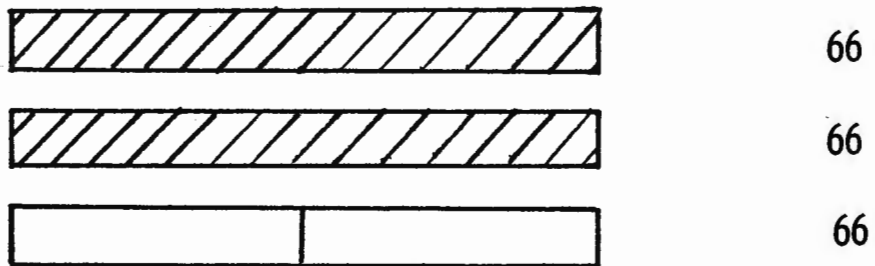
SAVINGS = 100

SYSTEM OPTIMIZATION

TWO ROBOTS/ONE OPERATOR



OPTIMAL DISTRIBUTION $\frac{1}{3}, \frac{1}{3}, \frac{1}{3}$



SAVINGS = 134

EXAMPLE
MULTIPLE ROBOT ANALYSIS

NO. ROBOTS	A	B	C	D		
	% SAVINGS PER OPERATION	TOTAL ROBOT COST	SAVINGS PER SHIFT	1 SHIFT	ROI 2 SHIFTS	3 SHIFTS
1	40.5	100	9,584	4.5	15.4	25.0
2	52.6	200	24,894	8.0	21.2	33.2
3	63.0	300	44,724	10.8	26.0	40.3
4	69.6	400	65,880	12.5	29.0	44.9
5	74.3	500	87,910	13.7	31.1	48.2

ASSUMPTIONS

- A. ROBOT PERFORMS AT OPERATOR'S NORMAL PACE
 - 1.15 AVG. P&F
 - 1.15 WAF TOTAL
 - 130% INCENTIVE OPPORTUNITY
 - 10% OF INC. STD. REMAINS AS "D" TIME
- B. \$100,000 PER ROBOT SYSTEM
\$20,000 SALVAGE VALUE
- C. SAVINGS = 8 HRS/SHIFT X 232 DAYS/YR X 85% UTILIZATION X \$15/HR X % SAVINGS
- D. BASED ON NUMBER OF SHIFTS OF CURRENT WORK LOAD

EXAMPLE: FOUR OPERATIONS - OPERATOR WORK PERCENTAGES

% OPER ₁	=	.90	} WITHOUT BALANCING OF RANDOM WORKCELLS, THESE OPERATIONS WOULD BE EXCLUDED FROM ROBOTIC AUTOMATION DUE TO THE HIGH % OF MANUAL WORK ELEMENTS.
% OPER ₂	=	.25	
% OPER ₃	=	.30	
% OPER ₄	=	.70	

BY BALANCING, WE WOULD TRY TO RUN JOBS (1) AND (2) TOGETHER,
AND (3) AND (4) TOGETHER.

BENEFITS OF SYSTEMS APPROACH

- GREATER SAVINGS → GREATER ROI'S
- ABLE TO BALANCE LOW ROBOT PERCENT OPERATIONS WITH HIGH ROBOT PERCENT OPERATIONS
- MAY START EFFECTING OVERHEAD ACCOUNTS FOR EVEN GREATER SAVINGS

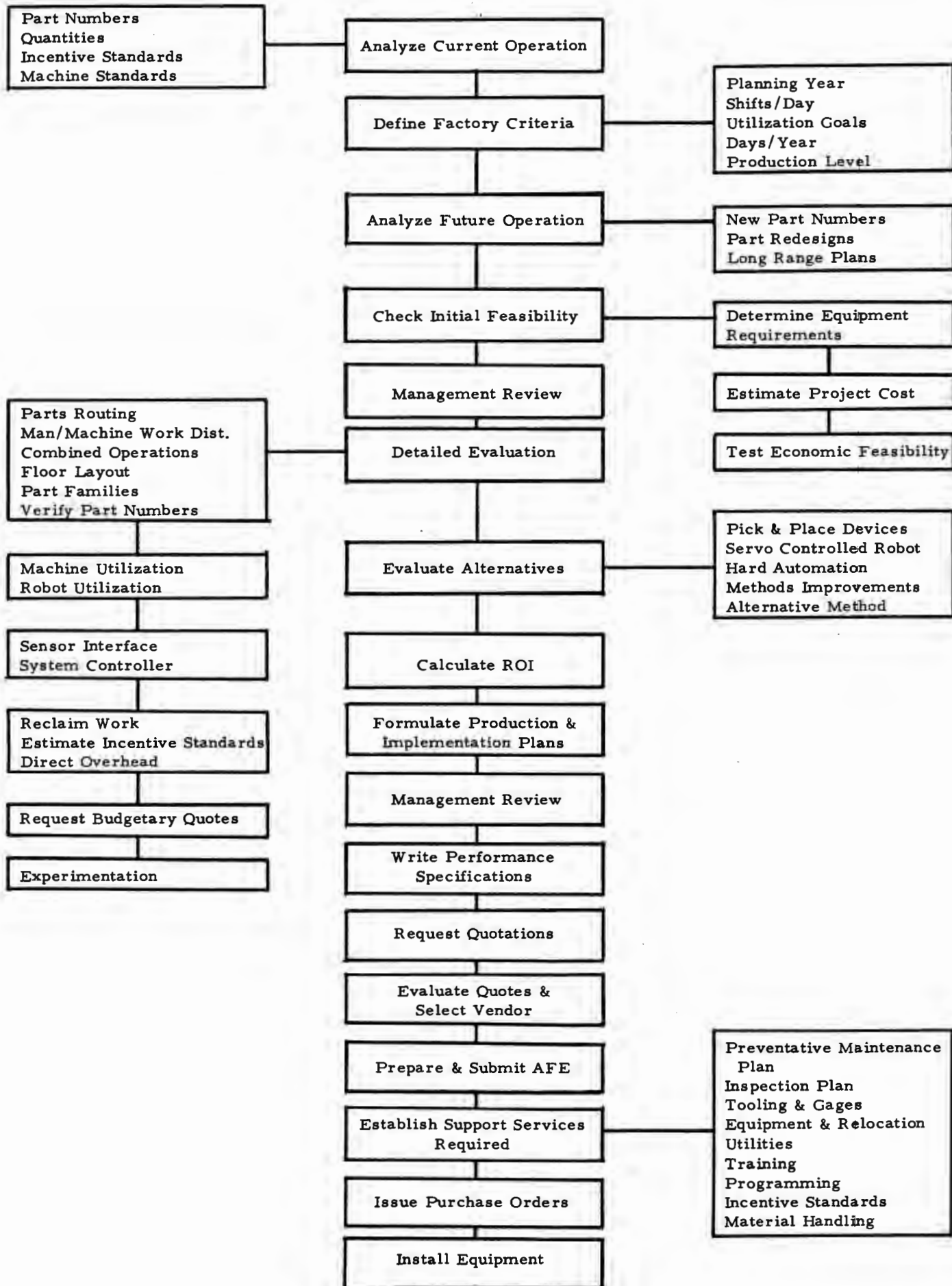
ADVANTAGES OF ANALYTICAL TOOLS

- TEST SENSITIVITY
- KNOW WHAT THE VARIABLES ARE
- CONCENTRATE ON IMPORTANT VARIABLES

SUMMARY OF ANALYTICAL TOOLS

<u>TOOL</u>	<u>USE</u>
OPTIMAL DIVISION OF WORK ELEMENTS	BALANCE WORK ELEMENTS TO MAXIMIZE ROBOT AND OPERATOR UTILIZATION
ROBOT ANALYSIS	DETERMINES JUSTIFIABLE CAPITAL EXPENDITURE, TOTAL HOURS, OR % REDUCTION
LOW HOUR ANALYSIS	HELPS ANALYZE AUTOMATION OF LOW HOUR OPERATIONS
SYSTEMS ANALYSIS	FOR MULTIPLE ROBOT APPLICATIONS
EXPENDITURE CONVERSION CHART	CONVERTS JUSTIFIABLE CAPITAL AT VARYING ROI'S AND START-UP DELAYS

ROBOT APPLICATION LOGIC CHART



SUMMARY

- ANALYTICAL TOOLS ARE AVAILABLE TO ASSIST ENGINEERS WITH ROBOT INVESTIGATIONS
- ROBOTS DO NOT HAVE TO PERFORM ALL TASKS CURRENTLY BEING PERFORMED BY OPERATORS
- MULTIPLE ROBOTIC SYSTEMS PROVIDE BENEFITS THAT MAY NOT BE OBTAINED IN SINGLE ROBOT SYSTEMS
- ROBOTS CAN WORK WITHIN THE DEERE INCENTIVE SYSTEM
- OPERATORS ARE AFFORDED GOOD INCENTIVE OPPORTUNITY